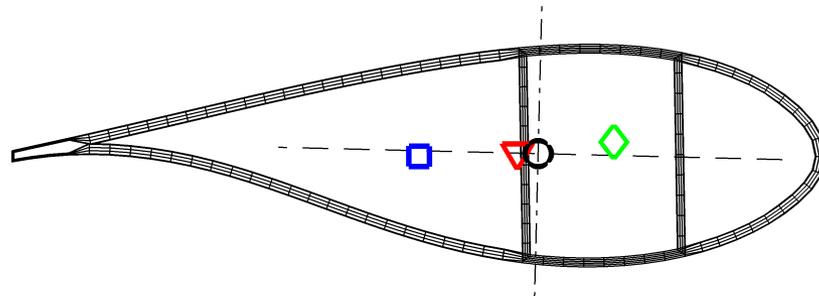
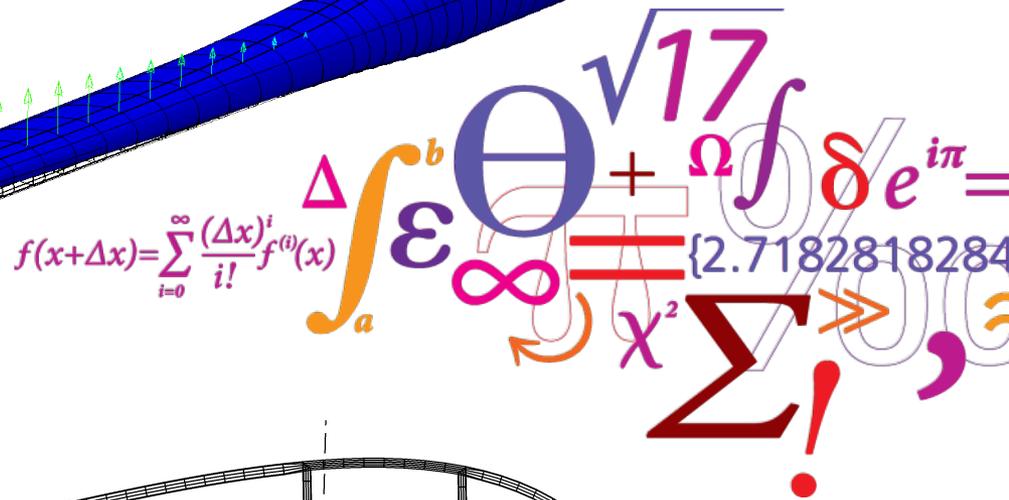
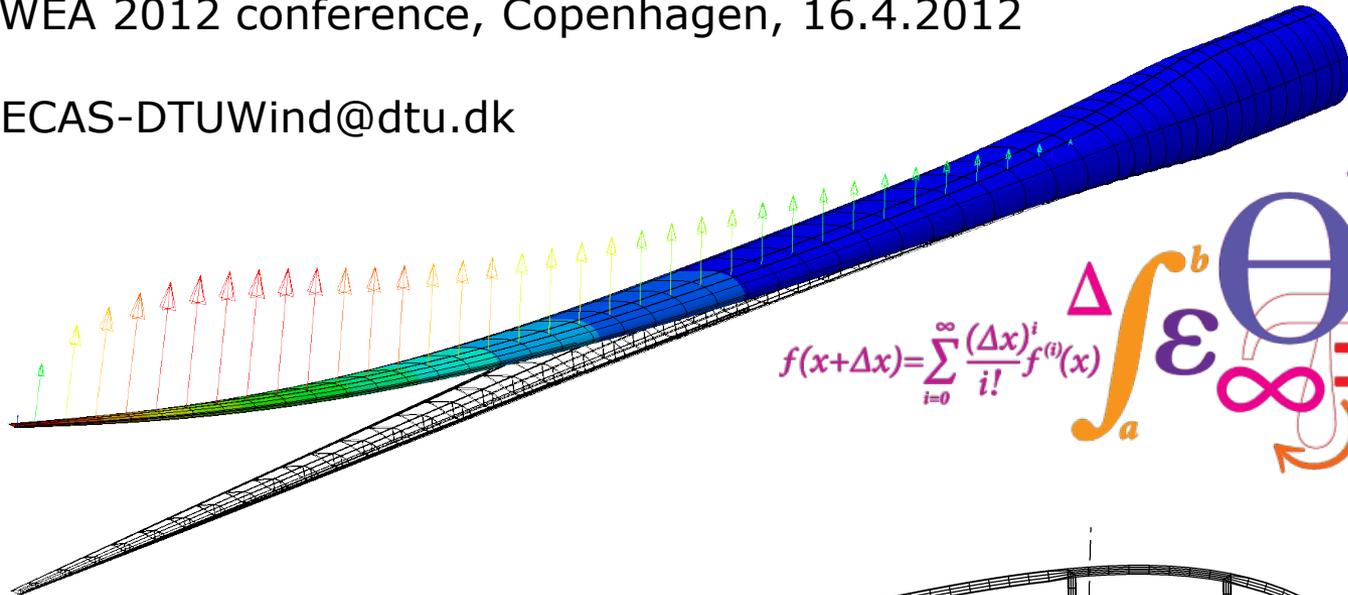


BECAS - an Open-Source Cross Section Analysis Tool

José P. Blasques and Robert D. Bitsche

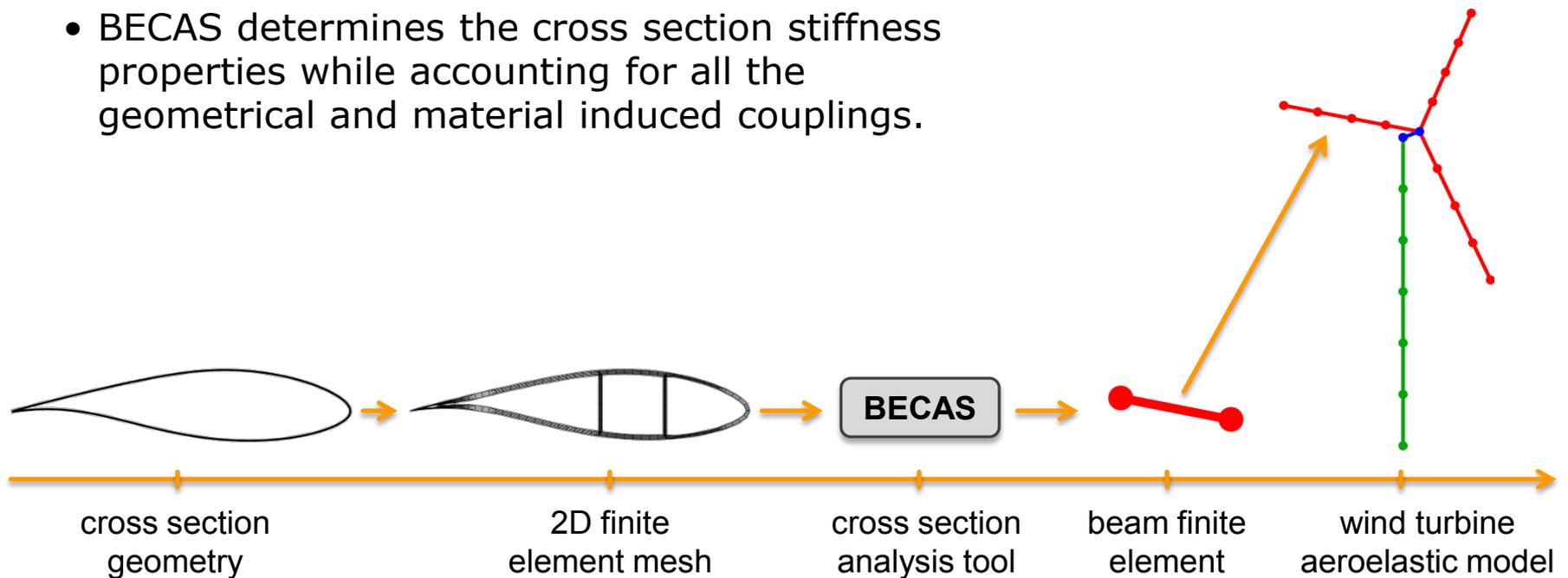
Presented at DTU Wind Energy stand at the
EWEA 2012 conference, Copenhagen, 16.4.2012

BECAS-DTUWind@dtu.dk

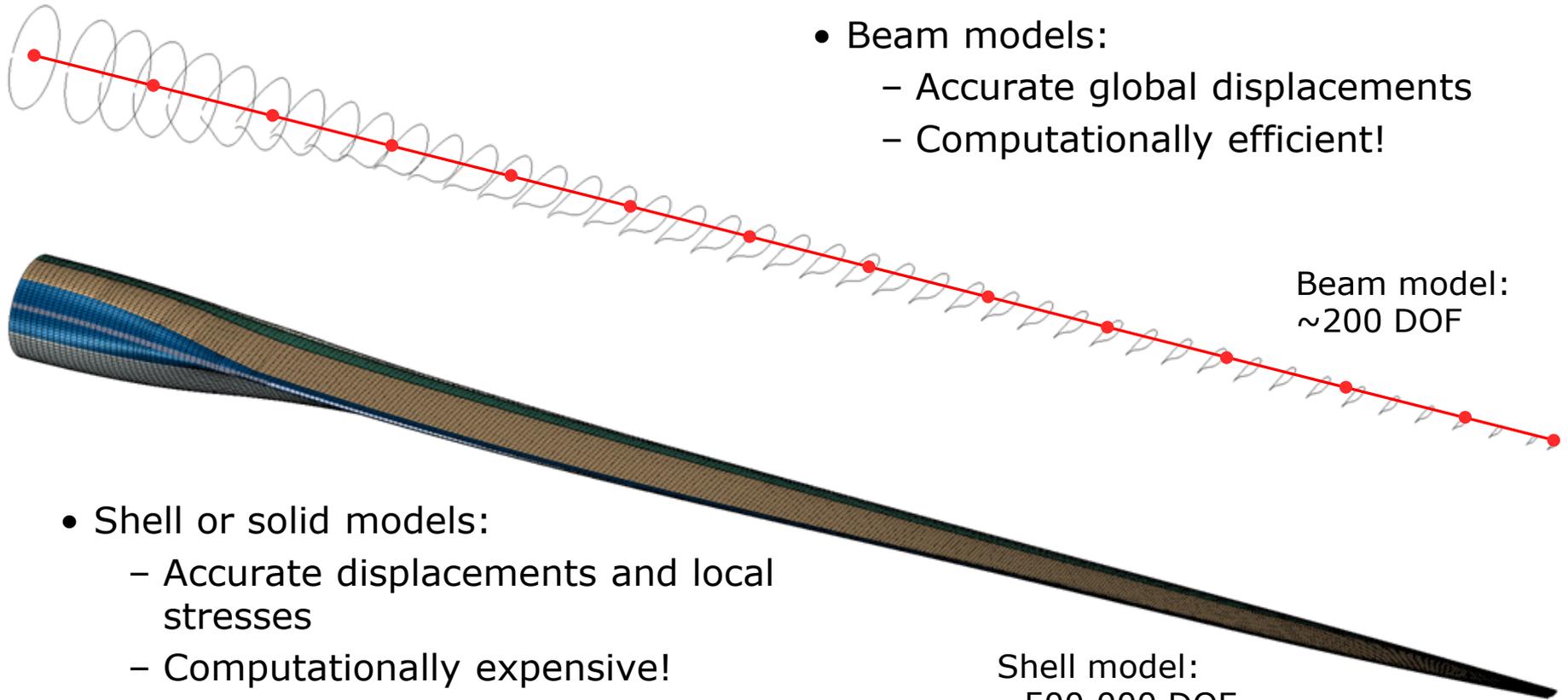


Motivation & Overview

- Wind turbine aeroelastic codes are commonly based on beam theory.
- The development of beam models which accurately describe the behavior of the blades is challenging, as modern wind turbine blades feature complex geometry and a mix of different anisotropic materials.
- BECAS is a general purpose cross section analysis tool specifically developed for these types of applications.
- BECAS determines the cross section stiffness properties while accounting for all the geometrical and material induced couplings.



Why Beam Models?



- Beam models:
 - Accurate global displacements
 - Computationally efficient!

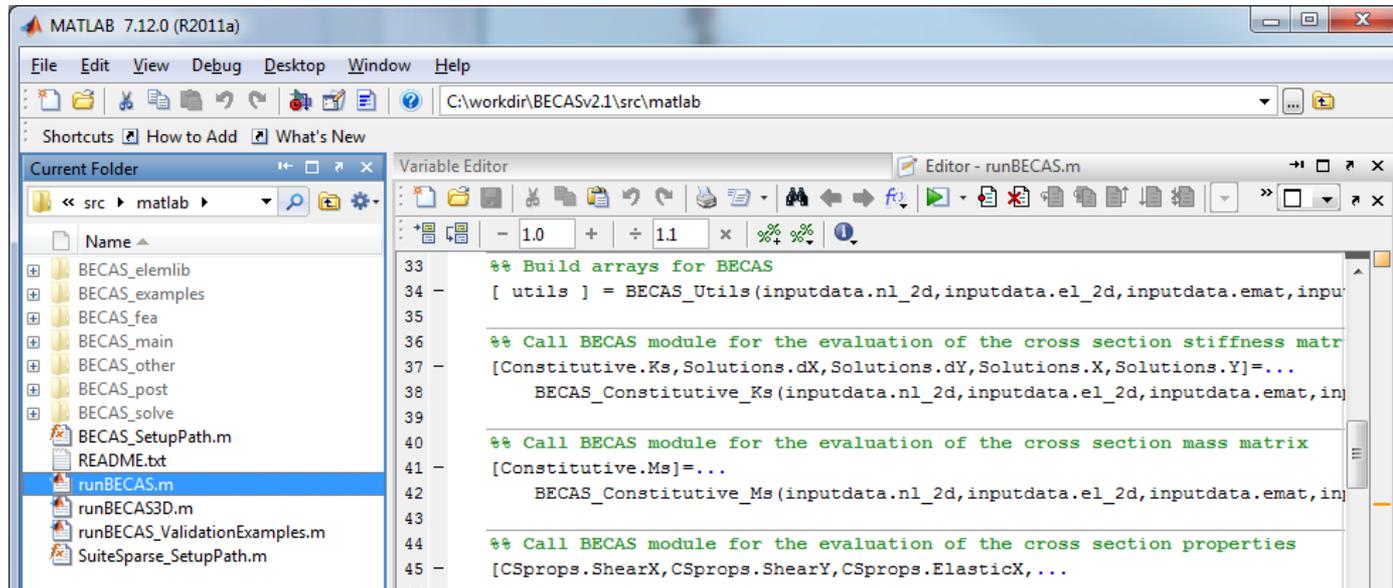
Beam model:
~200 DOF

- Shell or solid models:
 - Accurate displacements and local stresses
 - Computationally expensive!

Shell model:
~500.000 DOF

Theory

- BECAS is based on the theory originally presented by Giavotto et al.⁽¹⁾
- It was implemented as a set of Matlab[®] functions by José P. Blasques⁽²⁾.



```

33 %% Build arrays for BECAS
34 [ utils ] = BECAS_Utils(inputdata.nl_2d,inputdata.el_2d,inputdata.emat,inpu
35
36 %% Call BECAS module for the evaluation of the cross section stiffness matr
37 [Constitutive.Ks,Solutions.dX,Solutions.dY,Solutions.X,Solutions.Y]=...
38     BECAS_Constitutive_Ks(inputdata.nl_2d,inputdata.el_2d,inputdata.emat,in
39
40 %% Call BECAS module for the evaluation of the cross section mass matrix
41 [Constitutive.Ms]=...
42     BECAS_Constitutive_Ms(inputdata.nl_2d,inputdata.el_2d,inputdata.emat,in
43
44 %% Call BECAS module for the evaluation of the cross section properties
45 [CSprops.ShearX,CSprops.ShearY,CSprops.ElasticX,...

```

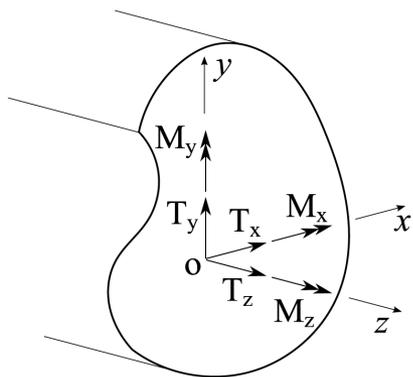
- (1) Giavotto V., Borri M., Mantegazza P., Ghiringhelli G., Carmaschi V., Maffioli G.C., Mussi F., *Anisotropic beam theory and applications*, Composite Structures, (16)1-4, 403-413, 1983
- (2) Blasques J. P., User's Manual for BECAS v2.0 - A cross section analysis tool for anisotropic and inhomogeneous beam sections of arbitrary geometry, DTU-RISØ, Technical Report RISØ-R 1785, 2011

Theory

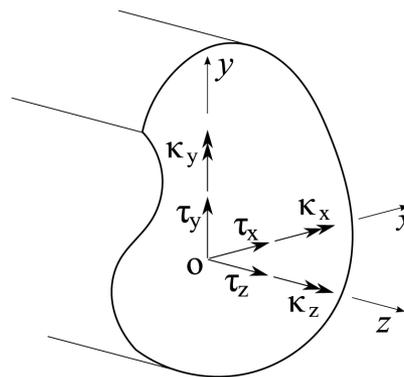
For a linear elastic beam there exists a linear relation between the vector of cross section forces and moments θ , and the resulting strains and curvatures ψ :

$$\theta = \mathbf{K}\psi$$

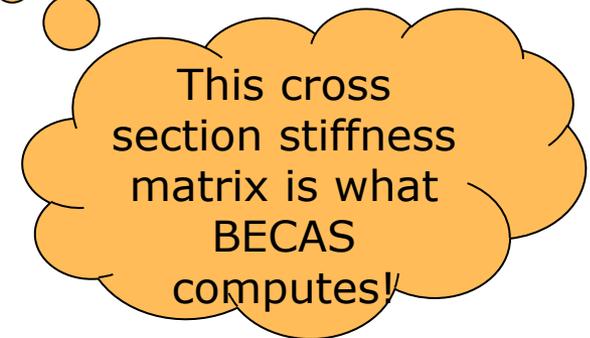
$$\begin{bmatrix} T_x \\ T_y \\ T_z \\ M_x \\ M_y \\ M_z \end{bmatrix} = \begin{bmatrix} K_{11} & K_{12} & K_{13} & K_{14} & K_{15} & K_{16} \\ K_{21} & K_{22} & K_{23} & K_{24} & K_{25} & K_{26} \\ K_{31} & K_{32} & K_{33} & K_{34} & K_{35} & K_{36} \\ K_{41} & K_{42} & K_{43} & K_{44} & K_{45} & K_{46} \\ K_{51} & K_{52} & K_{53} & K_{54} & K_{55} & K_{56} \\ K_{61} & K_{62} & K_{63} & K_{64} & K_{65} & K_{66} \end{bmatrix} \begin{bmatrix} \tau_x \\ \tau_y \\ \tau_z \\ \kappa_x \\ \kappa_y \\ \kappa_z \end{bmatrix}$$



(a) Forces and moments

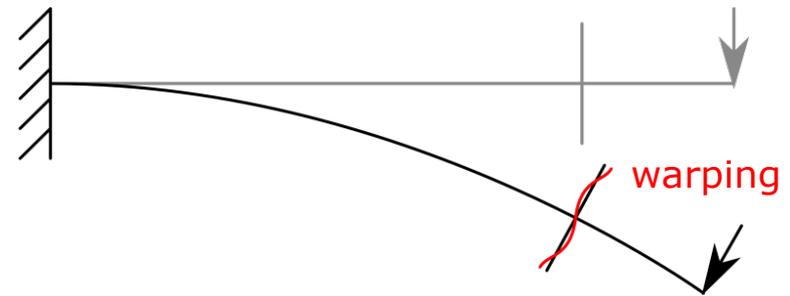


(b) Strains and curvatures

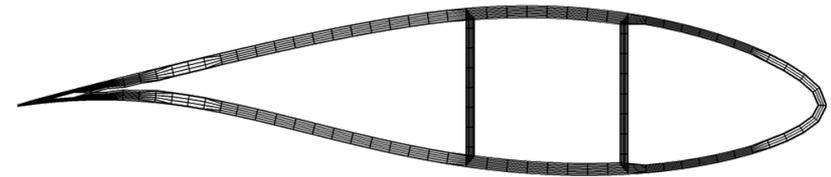


Theory

- It is assumed that the cross section deformation is defined by a superimposition of the rigid body motions and warping deformations.
- The cross section is discretized using two dimensional finite elements to interpolate the 3D warping deformations.
- Application of the principle of virtual work yields the finite element form of the cross section equilibrium equations.
- These equations allow to determine the resulting vector of strains and curvatures for a given vector of cross section forces and moments.
- If 6 vectors of strains and curvatures are determined for 6 "unit loads", the 6x6 cross section stiffness matrix K can be determined.



2D finite element mesh

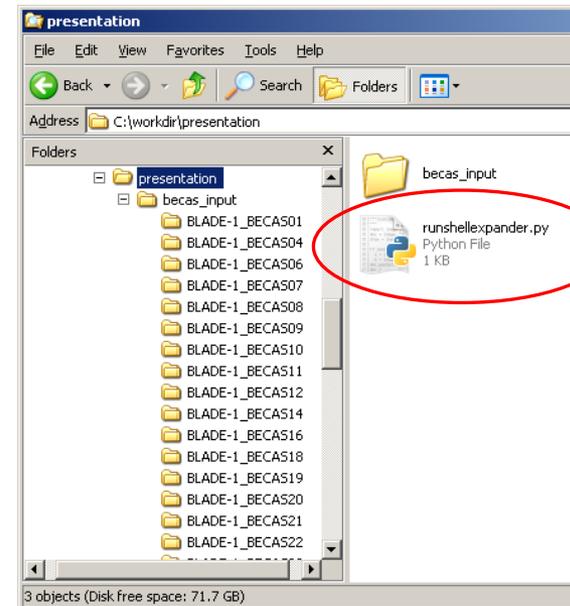
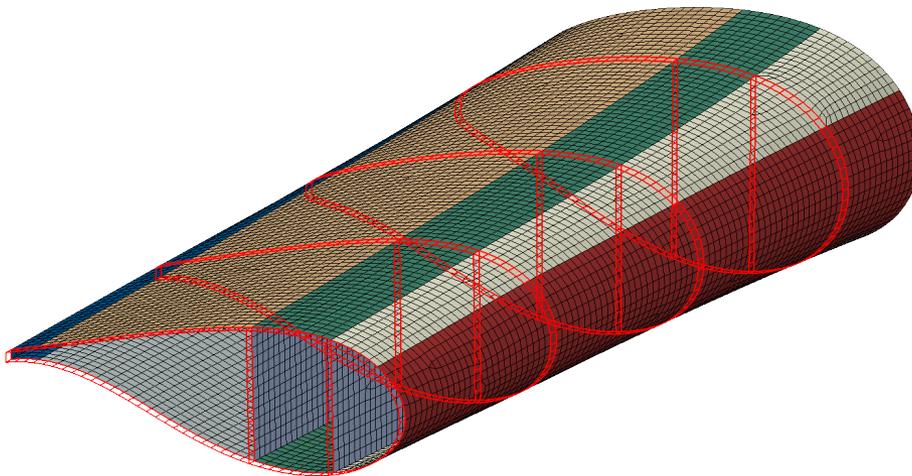
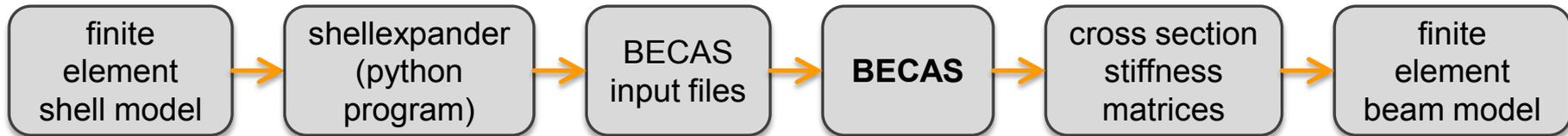


cross section equilibrium equations

$$\begin{cases} \mathbf{E} \frac{\partial \mathbf{u}}{\partial z} + \mathbf{R} \frac{\partial \psi}{\partial z} = 0 \\ \mathbf{R}^T \frac{\partial \mathbf{u}}{\partial z} + \mathbf{A} \frac{\partial \psi}{\partial z} = \frac{\partial \boldsymbol{\theta}}{\partial z} \end{cases}$$

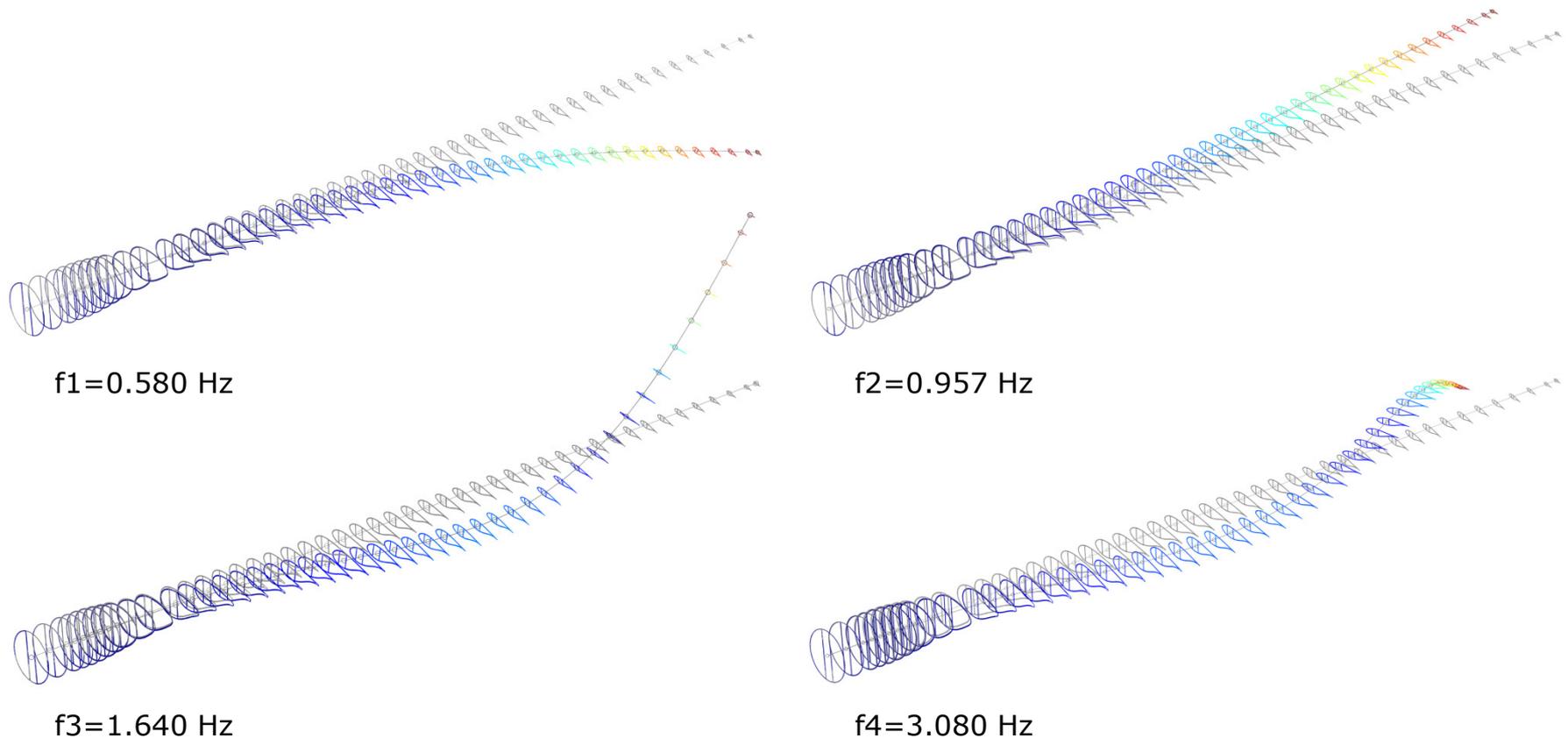
$$\begin{cases} \mathbf{E} \mathbf{u} + \mathbf{R} \psi = (\mathbf{C} - \mathbf{C}^T) \frac{\partial \mathbf{u}}{\partial z} + \mathbf{L} \frac{\partial \psi}{\partial z} \\ \mathbf{R}^T \mathbf{u} + \mathbf{A} \psi = -\mathbf{L}^T \frac{\partial \mathbf{u}}{\partial z} + \boldsymbol{\theta} \end{cases}$$

Example: Analysis of a Wind Turbine Blade



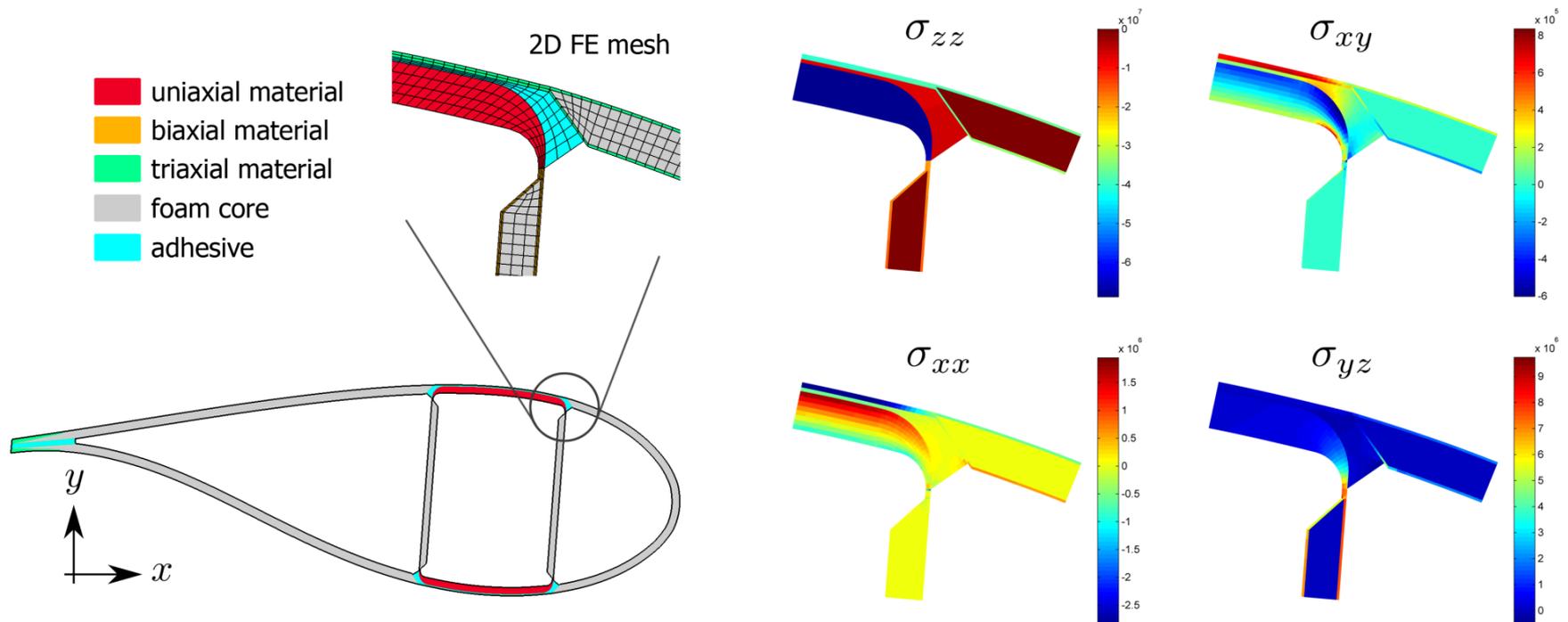
Example: Analysis of a Wind Turbine Blade

- Eigenfrequencies obtained from the BECAS-based beam model match the results from the original finite element shell model.



Outlook: Stress Recovery

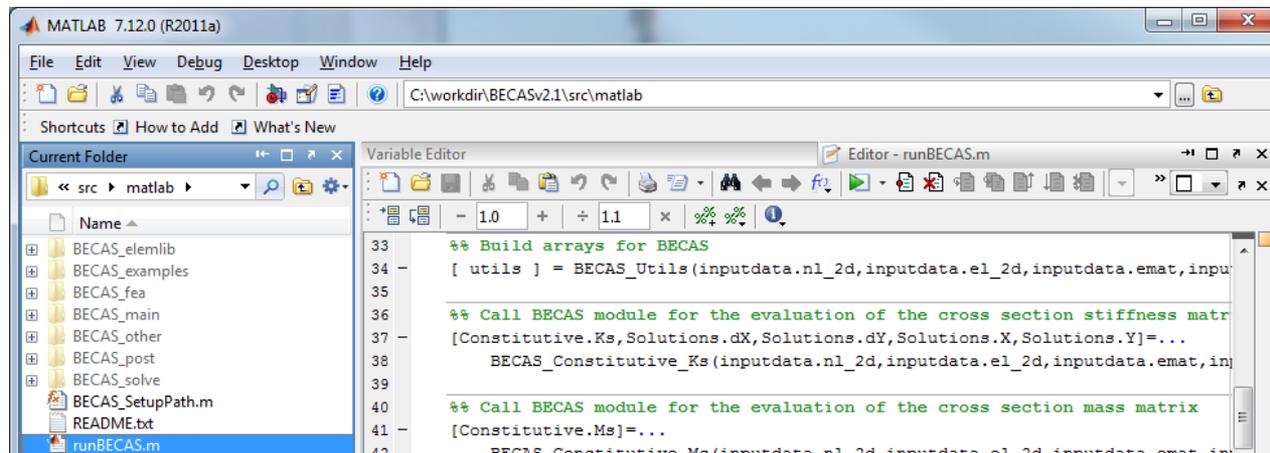
- The cross section forces and moments coming from a beam model can be used to compute the local 3D stresses for each cross section.



- In the process of being validated.
- Will be part of a future release of BECAS.

Why choose BECAS?

- Many other cross section analysis tools are available – why choose BECAS?
 - BECAS is distributed as Matlab[®] source code.
 - Alternatively it is available as a compiled version, which does not require a Matlab license.
 - The license is free of charge for academic use.
 - BECAS has been validated extensively and comes with a comprehensive user's manual.
 - BECAS is fast, when used with the free SuiteSparse package.
 - Integrated with HAWC2



Thank you.

Further information?

Mail: BECAS-DTUWind@dtu.dk